

Simulasi linear quadratic regulator waktu-kontinu untuk kontrol balik optimal suatu sistem skalar

Deskripsi Lengkap: <https://lib.ui.ac.id/detail?id=118746&lokasi=lokal>

Abstrak

This paper discusses optimal control of continuous-time systems, especially continuous-time linear quadratic regulator (LQR). The LQR will be implemented to determine the optimal feedback control of a scalar system.....